

## Review of Multi-variable calculus:

The functions in all models depend on two variables: time  $t$  and spatial variable  $x$ ,  $(x, y)$  or  $(x, y, z)$ .

The spatial variable represents the environment where the species is living (bacteria: tank in lab, rabbits and foxes: woods, birds: the space).

The time variable is one dimension, we call it **time interval**. Usually it is  $(-\infty, \infty)$ ,  $[0, \infty)$  or  $[0, T]$ .

In mathematics we call the environment **spatial domain** (or simply **domain**) , or **region**.

## Domains

The choice of domain in a model depends on the nature of the problem.

Most of time, domain is bounded. (lab tank, woods, island, earth, universe?). And it has a boundary.

Mathematically we assume that a bounded domain is an interval  $(a, b)$  in 1-d, the region enclosed by a circular curve in 2-d, or the region enclosed by a spherical surface in 3-d.

Sometime for simplicity, or to observe certain phenomenon clearer, we also consider the whole space  $\mathbf{R} = (-\infty, \infty)$ ,  $\mathbf{R}^2$  or  $\mathbf{R}^3$ .

We will call a domain  $\Omega$ .

## Functions

Functions in the models are defined for (time interval  $\times$  domain).

Let  $X$  be  $x$ ,  $(x, y)$  or  $(x, y, z)$ . Then the function is in a form of  $f(t, X)$ .

Example: Let  $D$  be a 2-d domain. (a woods)

$R(t, x, y)$  = the density of rabbit population at location  $(x, y)$  and time  $t$

$F(t, x, y)$  = the density of fox population at location  $(x, y)$  and time  $t$

Population density =  $\frac{\text{total population in an area}}{\text{area}}$

Example: population density is 50,000 per square kilometer in NYC, and it is 5,000 in Williamsburg

**Graph of the function:** (hard to draw in 2-d or 3-d)

graph:  $(x, y, f(x, y))$  (Maple),  $(x, y, z, f(x, y, z))$ .

level curve (contour): the graph of  $f(x, y) = c$ . (Maple)

level surface: the graph of  $f(x, y, z) = c$ . (Maple)

Derivatives: partial derivatives  $\frac{\partial f(t, x, y)}{\partial t} = f_t$ ,  $\frac{\partial f(t, x, y)}{\partial x} = f_x$

Gradient:  $\nabla f(x, y) = (\partial f / \partial x, \partial f / \partial y)$

Gradient at one point is a vector; gradient function is a vector field; gradient vector is perpendicular to the level curve

Vector field: (a vector)  $F(x, y) = (f(x, y), g(x, y))$

Jacobian: (a matrix)  $J = \begin{pmatrix} f_x(x, y) & f_y(x, y) \\ g_x(x, y) & g_y(x, y) \end{pmatrix}$

Divergent of a vector field: (a scalar)  
for  $F(x, y) = (f(x, y), g(x, y))$ ,  $\text{div}(F) = f_x + g_y$

Laplacian of a function: (a scalar)  
for a function  $f(x, y)$ ,  $\Delta f = \text{div}(\nabla f) = \text{div}(f_x, f_y) = f_{xx} + f_{yy}$

Hessian of a function: (a matrix)  
for a function  $f(x, y)$ , Jacobian of  $\nabla f$ ,  $H = \begin{pmatrix} f_{xx}(x, y) & f_{xy}(x, y) \\ f_{yx}(x, y) & f_{yy}(x, y) \end{pmatrix}$

Example:  $f(x, y) = x^2 + 2y^2 - 2xy$ .

(1) Find  $\nabla f$ ; (2) Find Hessian of  $f$ ; (3) Find  $\Delta f$ .

## Different kinds of functions:

$P(t)$ : function (one variable, one function)

$P(x, y)$ : multi-variable function (two variables, one function)

$(P(t), Q(t))$ : vector valued function (one variable, two functions)

$(P(x, y), Q(x, y))$ : vector field (two variables, two functions)

**Integral of functions:**  $\Omega$ : two-dimensional domain, boundary  $\partial\Omega$  a closed curve,  $X = (x, y)$

$$\int_{\Omega} f(x, y) dX = \int \int_{\Omega} f(x, y) dx dy \quad \int_{\Omega} 1 dX = \text{area of } \Omega$$

**Divergence Theorem:**

Let  $\vec{F}(x, y)$  be a vector field, and let  $\vec{n}(x, y)$  be the unit outer normal vector at  $(x, y)$ , a boundary point on  $\partial\Omega$ . Then  $\int_{\partial\Omega} \vec{F}(x, y) \cdot \vec{n}(x, y) ds$  is the total flux of  $\vec{F}$  over the curve  $\partial\Omega$ .

$$\int_{\partial\Omega} \vec{F}(x, y) \cdot \vec{n}(x, y) ds = \int_{\Omega} \text{div}(\vec{F}(x, y)) dX.$$

1-d:  $F(b) - F(a) = \int_a^b F'(x) dx$

## Green's Identities:

$$\int_{\Omega} u \Delta v dX = \int_{\partial\Omega} u \nabla v \cdot \vec{n} ds - \int_{\Omega} \nabla u \cdot \nabla v dX$$

$$\int_{\Omega} u \Delta v dX - \int_{\Omega} v \Delta u dX = \int_{\partial\Omega} u \nabla v \cdot \vec{n} ds - \int_{\partial\Omega} v \nabla u \cdot \vec{n} ds$$

Example: Let  $F(x, y) = (x + y, e^{x-y})$ , and let  $\Omega$  be a square  $(0, 1) \times (0, 1)$ .

(1) Calculate  $\int_{\Omega} \operatorname{div}(\vec{F}(x, y)) dX$

(2) calculate  $\int_{\partial\Omega} \vec{F}(x, y) \cdot \vec{n}(x, y) ds$