# Once Upon a Time...

#### Constant diffusion:

$$J = -D \, \nabla \cdot u$$

$$\frac{\partial u}{\partial t} = -\nabla \cdot J = D \,\Delta \,u$$

But is this truly realistic???

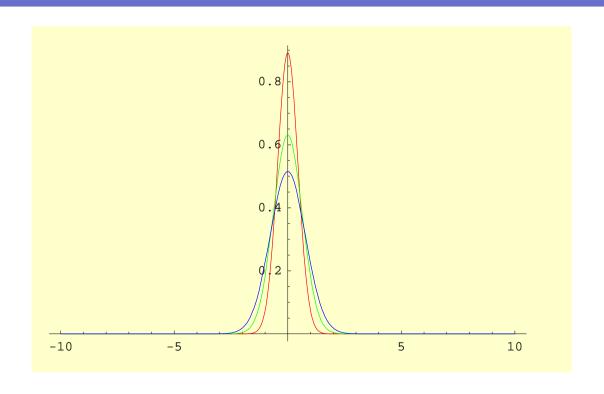
#### **Problems With Constant Diffusion**

Any initial condition, even a point distribution, instantly "spreads out" to cover an infinite domain. Consider the one-dimensional case:

$$\begin{cases} \frac{\partial u}{\partial t} = D \frac{\partial^2 u}{\partial x^2} \\ u(x, 0) = \delta(x) \end{cases}$$

$$\Rightarrow u(x, t) = \frac{1}{\sqrt{4\pi Dt}} \exp\left(-\frac{x^2}{4Dt}\right)$$

## **Problems With Constant Diffusion**



## **How Can We Improve This?**

Use a non-constant diffusion term:

$$J = -D(u) \nabla \cdot u(x, t)$$

$$\frac{\partial u}{\partial t} = -\nabla \cdot J = \nabla \cdot (D(u) \nabla \cdot u)$$

This makes intuitive sense - in an insect population, for example, we would expect very densely populated areas to diffuse outwards more quickly than sparsely populated areas.

# Crap!

Of course, now we need to figure out how to deal with non-constant diffusion in our solution.

Rewrite our equation as

$$\frac{\partial u}{\partial t} - \nabla \cdot (D(u) \nabla \cdot u) = 0$$

We can consider this to be an example of a general class of functions of the form

$$G(x, t, u, u_x, u_t, u_{xx}, u_{xt}, u_{tt}) = 0$$

The one-parameter family of stretching functions:

$$\overline{x} = \epsilon^a x$$

$$\bar{t} = \epsilon^b t$$

$$\overline{u} = \epsilon^c u$$

The *one-parameter family of stretching functions*:

$$\overline{x} = \epsilon^a x$$

$$\overline{t} = \epsilon^b t$$

$$\overline{u} = \epsilon^c u$$

a, b, and c are constants;  $\epsilon$  is a real parameter on some open interval that contains 1.

Define G to be *invariant* if there exists a smooth function  $f(\epsilon)$  such that

$$G(\overline{x}, \overline{t}, \overline{u}, \overline{u}_{\overline{x}}, \overline{u}_{\overline{t}}, \overline{u}_{\overline{x}\overline{x}}, \overline{u}_{\overline{t}}, \overline{u}_{\overline{t}}) = f(\epsilon) G(x, t, u, u_x, u_t, u_{xx}, u_{xt}, u_{tt})$$

Assume G is invariant. This gives us

$$G(\overline{x}, \overline{t}, \overline{u}) = f(\epsilon) G(x, t, u)$$

$$G(\epsilon^a x, \epsilon^b t, \epsilon^c u) = f(\epsilon) G(x, t, u)$$

$$G(\epsilon^a x, \epsilon^b t, \epsilon^c u) = f(\epsilon)(0)$$

$$G(\epsilon^a x, \epsilon^b t, \epsilon^c u) = 0$$

(Because *G* is homogenous.)

Differentiate with respect to  $\epsilon$ :

$$ax\epsilon^a \frac{\partial G}{\partial x} + bt\epsilon^b \frac{\partial G}{\partial t} + cu\epsilon^c \frac{\partial G}{\partial u} = 0$$

Set  $\epsilon = 1$  (which we can do because we restrict  $\epsilon$  to a domain that contains 1):

$$ax\frac{\partial G}{\partial x} + bt\frac{\partial G}{\partial t} + cu\frac{\partial G}{\partial u} = 0$$

Clever people look at this and see that the transformation we want to use is

$$u = t^{c/b} r(z)$$

$$z = \frac{x}{t^{a/b}}$$

Verification of the transformation:

$$ax \frac{\partial G}{\partial x} + bt \frac{\partial G}{\partial t} + cu \frac{\partial G}{\partial u} = 0$$

$$ax \frac{\partial G}{\partial z} \frac{\partial z}{\partial x} + bt \frac{\partial G}{\partial z} \frac{\partial z}{\partial t} + cu \frac{\partial G}{\partial z} \frac{\partial z}{\partial u} = 0$$

$$\frac{\partial z}{\partial x} = \frac{1}{t^{a/b}}, \frac{\partial z}{\partial t} = \cdots$$

What have we accomplished with all our fancy math?

$$G(x, t, u, u_x, u_t, u_{xx}, u_{xt}, u_{tt}) = 0$$

$$\iff$$

$$g(z, r, r', r'') = 0$$

Recall the problem we're actually working on:

$$\frac{\partial u}{\partial t} = \nabla \cdot (D(u) \, \nabla \cdot u)$$

$$D(u) = D_0 \left(\frac{u}{u_0}\right)^m$$

Letting m = 1 gives us

$$\frac{\partial u}{\partial t} = \frac{\partial}{\partial x} \left( \frac{D_0}{u_0} u \frac{\partial u}{\partial x} \right)$$

And because we're lazy, we'll assume  $\frac{D_0}{u_0} = 1$ , so

$$\frac{\partial u}{\partial t} = \frac{\partial}{\partial x} \left( u \, \frac{\partial u}{\partial x} \right)$$

The problem is now

$$\begin{cases} \frac{\partial u}{\partial t} = \frac{\partial}{\partial x} \left( u \frac{\partial u}{\partial x} \right) \\ u(x, 0) = \delta(x) \end{cases}$$

Other assumptions:

Since no organisms are being born or dying, we require for all t > 0

$$\int_{-\infty}^{\infty} u(x, t) \, dx = 1$$

and

$$\lim_{x \to +\infty} u(x, t) = 0$$

#### Check for invariance:

$$G(\overline{x}, \overline{t}, \overline{u}, \overline{u}_{\overline{x}}, \overline{u}_{\overline{t}}, \overline{u}_{\overline{x}\overline{x}}, \overline{u}_{\overline{t}\overline{t}}, \overline{u}_{\overline{t}t}) = f(\epsilon) G(x, t, u, u_x, u_t, u_{xx}, u_{xt}, u_{tt})$$

$$\overline{x} = \epsilon^a x$$

$$\bar{t} = \epsilon^b t$$

$$\overline{u} = \epsilon^c u$$

$$\frac{\partial \overline{u}}{\partial \overline{t}} - \frac{\partial}{\partial \overline{x}} \left( \overline{u} \frac{\partial \overline{u}}{\partial \overline{x}} \right) = \epsilon^{c-b} \frac{\partial u}{\partial t} - \epsilon^{2c-2a} \frac{\partial}{\partial x} \left( u \frac{\partial u}{\partial x} \right)$$

We have invariance if

$$c - b = 2 c - 2 a \Rightarrow c = 2 a - b$$

$$u = t^{c/b} r(z)$$

$$z = \frac{x}{t^{a/b}}$$

With our invariance condition,

$$u = t^{(2a-b)/b} r(z)$$

$$z = \frac{x}{t^{a/b}}$$

#### Let's be clever:

$$\int_{-\infty}^{\infty} u(x, t) dx = 1$$

$$t^{(2a-b)/b} \int_{-\infty}^{\infty} r\left(\frac{x}{t^{a/b}}\right) dx = 1$$

$$t^{(3a-b)/b} \int_{-\infty}^{\infty} r(z) dz = 1$$

Time-independence requires

$$b = 3 a$$

Which simplifies the transformation to

$$u = t^{-1/3} r(z)$$
$$z = x t^{-1/3}$$

$$\begin{cases} \frac{\partial u}{\partial t} = \frac{\partial}{\partial x} \left( u \frac{\partial u}{\partial x} \right) \\ u = t^{-1/3} r(z) \Longrightarrow 3 (r r')' + r + z r' = 0 \\ z = x t^{-1/3} \end{cases}$$

This equation can be integrated to give

$$3rr' + zr = constant$$

Take the constant to be zero; the solution is

$$r(z) = \frac{A^2 - z^2}{6}$$

Use our conditions to clean it up:

$$\lim_{x \to \pm \infty} u(x, t) = 0$$

means that

$$r(z) = \begin{cases} \frac{A^2 - z^2}{6}, & |x| < A \\ 0 & |x| > A \end{cases}$$

And

$$\int_{-\infty}^{\infty} u(x, t) \, dx = 1$$

means that

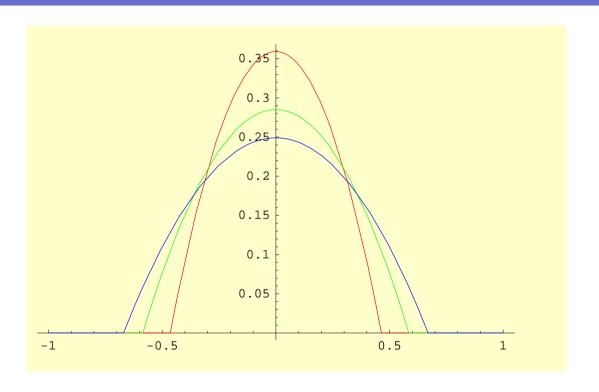
$$A = \left(\frac{9}{2}\right)^{1/3}$$

Now switch everything back to original coordinates.

$$u(x, t) = \begin{cases} \frac{1}{6t} (A^2 t^{2/3} - x^2), & |x| < A t^{1/3} \\ 0 & |x| > A t^{1/3} \end{cases}$$

About time. Let's take a look!

# **A Specific Example - Pretty Pictures**



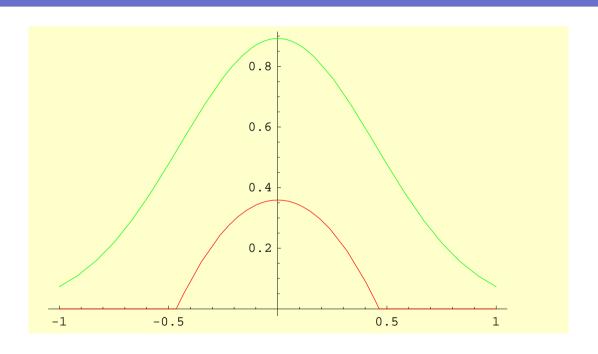
The key feature of this solution is the sharp wave front at

$$x_f = A t^{1/3}$$

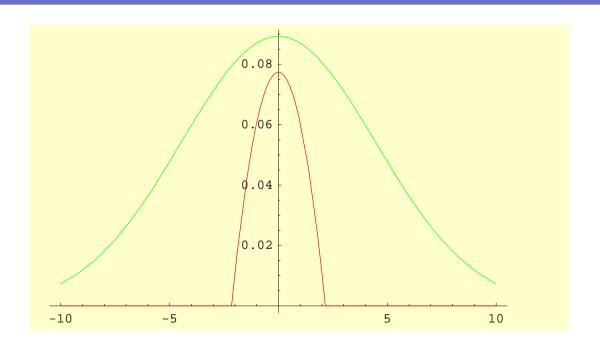
This wave is moving with speed

$$\frac{dx_f}{dt} = \frac{1}{3} A t^{-2/3}$$

# Comparing Constant and Density-Dependent Diffusion at t = .1



# Comparing Constant and Density-Dependent Diffusion at t = 10



## What About the Not-Simple Case, You Ask?

Recall that the general form is

$$\frac{\partial u}{\partial t} = \nabla \cdot (D(u) \, \nabla \cdot u)$$

$$D(u) = D_0 \left(\frac{u}{u_0}\right)^m$$

and we assumed m = 1 for all the work we just did. Is there a general solution?

## What About the Not-Simple Case, You Ask?

Yes, and here it is:

$$u(x, t) = \begin{cases} \frac{u_0}{\lambda(t)} \left( 1 - \left( \frac{x}{r_0 \lambda(t)} \right)^2 \right)^{1/m}, & |x| \le r_0 \lambda(t) \\ 0 & |x| > r_0 \lambda(t) \end{cases}$$

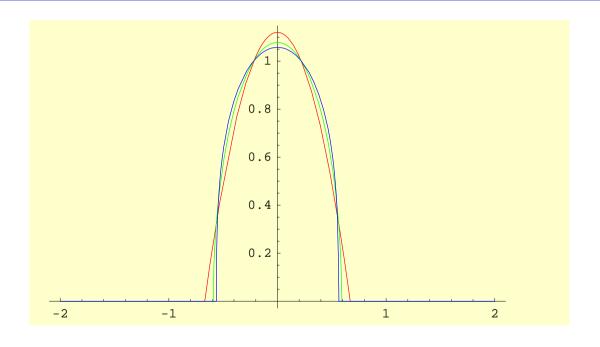
Where

$$\lambda(t) = \left(\frac{t}{t_0}\right)^{1/(2+m)}$$

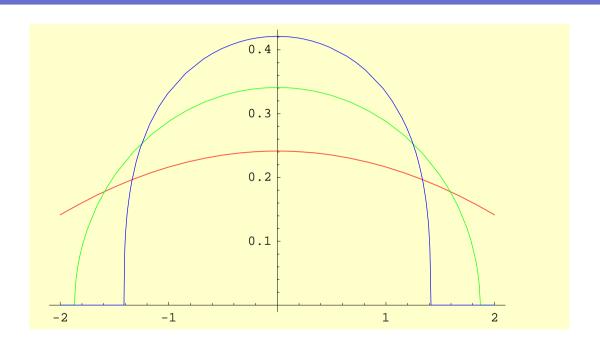
$$r_0 = \frac{Q\Gamma(\frac{1}{m} + \frac{3}{2})}{\pi^{1/2} u_0 \Gamma(\frac{1}{m} + 1)}, \quad t_0 = \frac{r_0^2 m}{2 D_0(m+2)}$$

 $D_0$  and  $n_0$  are positive constants; Q is the initial density at the origin, and  $r_0$  comes from requiring that the integral over the domain at all times be equal to Q.

# Not-Simple Case, t = .1 and m = 1, 2, 3



# Not-Simple Case, t = 10 and m = 1, 2, 3



# Pay No Attention to the Man Behind the Curtain

```
ln[30]:= u[x,t]:=
         Which [Abs[x] < t^{1/3}, \frac{1}{6t} (t^{2/3} - x^2), True, 0]
ln[31]:= uConstantD[x_, t_] := \frac{1}{\sqrt{4\pi +}} Exp\left[\frac{-x^2}{4t}\right]
       Plot[\{u[x, .1], u[x, .2], u[x, .3]\},
In[39]:=
           \{x, -1, 1\}, PlotStyle \rightarrow {RGBColor[1, 0, 0],
             RGBColor[0, 1, 0], RGBColor[0, 0, 1]}];
       Plot[\{u[x, .1], uConstantD[x, .1]\},
ln[40]:=
           \{x, -1, 1\}, PlotStyle \rightarrow {RGBColor[1, 0, 0],
             RGBColor[0, 1, 0], RGBColor[0, 0, 1]}];
```

```
\{x, -10, 10\}, PlotRange \rightarrow All,
                PlotStyle → {RGBColor[1, 0, 0],
                   RGBColor[0, 1, 0], RGBColor[0, 0, 1]}];
\ln[47] := \lambda \left[ t_{,m} \right] := \left( \frac{t}{t_{,m}} \right)^{\frac{1}{2+m}}
ln[48]:= r0[m_] := \frac{Gamma\left[\frac{1}{m} + 3/2\right]}{\sqrt{\pi} Gamma[1/m+1]}
ln[49] := t0[m] := \frac{r0[m]^2 * m}{2(m+1)}
           uGeneral[x_, t_, m_] :=
In[50]:=
              Which Abs [x] \le r0[m] \lambda[t, m],
                \frac{1}{\lambda \left[1 - \left(\frac{\mathbf{x}}{r_0[m] \lambda [t m]}\right)^2\right]^{1/m}}, \text{ True, } 0
```

 $Plot[\{u[x, 10], uConstantD[x, 10]\},$ 

In[46]:=

```
\{x, -2, 2\}, PlotRange \rightarrow All,
          PlotStyle → {RGBColor[1, 0, 0],
            RGBColor[0, 1, 0], RGBColor[0, 0, 1]}];
In[55]:=
       Plot[{uGeneral[x, 10, 1],
           uGeneral[x, 10, 2], uGeneral[x, 10, 3]},
          \{x, -2, 2\}, PlotRange \rightarrow All,
          PlotStyle \rightarrow {RGBColor[1, 0, 0],
            RGBColor[0, 1, 0], RGBColor[0, 0, 1]}];
```

uGeneral[x, .1, 2], uGeneral[x, .1, 3]},

Plot[{uGeneral[x, .1, 1],

In[54]:=