

# Reaction-Diffusion Models and Bifurcation Theory

## Lecture 8: Global bifurcation

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# Linear Functional Analysis

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- 7 Let  $L$  be a linear compact operator from  $X$  to  $X$ . Then  $I - L$  is a linear Fredholm operator with index 0.



# Elliptic Operators

Let  $\Omega$  be a bounded domain in  $\mathbb{R}^n$  with smooth boundary. Consider the Possion's equation

$$-\Delta u(x) = f(x), \quad x \in \Omega, \quad u(x) = 0, \quad x \in \partial\Omega.$$

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Let  $\Omega$  be a bounded domain in  $\mathbb{R}^n$  with smooth boundary. Consider the Poisson's equation

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- ④  $-\Delta$  is an invertible linear operator. Let  $K = (-\Delta)^{-1}$ . Then  $K : L^p(\Omega) \rightarrow W^{2,p}(\Omega) \cap W_0^{1,p}(\Omega)$  or  $K : C^\alpha(\overline{\Omega}) \rightarrow C_0^{2,\alpha}(\overline{\Omega})$  is a bounded linear operator. So  $(-\Delta)^{-1}$  is bounded.

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- 6 Hence  $(-\Delta)^{-1} = i \circ K : L^p(\Omega) \rightarrow L^p(\Omega)$  ( $C^\alpha(\overline{\Omega}) \rightarrow C^\alpha(\overline{\Omega})$ ) is a linear compact operator.

# Nonlinear Mappings

- 1 **Compact mapping:** a mapping  $F : X \rightarrow Y$  is compact if  $F$  is continuous, and for every bounded subset  $B$  of  $X$ , the image  $F(B) = \{F(u) : u \in B\}$  is a relatively compact subset of  $Y$ .

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Let  $L$  be a linear compact operator on  $X$ . From Riesz-Schauder theory, the set of eigenvalues of  $L$  is at most countably many, and the only possible limit point is  $\lambda = 0$ . For any eigenvalue  $\lambda$  of  $L$ , the subspace

$$X_\lambda = \bigcup_{n=1}^{\infty} \{u \in X : (L - \lambda I)^n u = 0\}$$

is finite dimensional, and  $\dim(X_\lambda)$  is the **algebraic multiplicity** of the eigenvalue  $\lambda$ . The **geometric multiplicity** of  $\lambda$  is defined as  $\dim\{u \in X : (L - \lambda I)u = 0\}$ .

# Krasnoselski-Rabinowitz Global Bifurcation Theorem

Consider

$$F(\lambda, u) = u - \lambda Lu - H(\lambda, u), \quad (1)$$

where  $L : X \rightarrow X$  is a linear compact operator, and  $H(\lambda, u)$  is compact on  $U \subset \mathbb{R} \times X$  such that  $\|H(\lambda, u)\| = o(\|u\|)$  near  $u = 0$  uniformly on bounded  $\lambda$  intervals. Note the conditions imply that  $F_u(\lambda, 0) = I - \lambda L$ , and if 0 is an eigenvalue of  $F_u(\lambda_0, 0)$ , then  $\lambda_0^{-1}$  must be an eigenvalue of the linear operator  $L$ . Define

$$S = \{(\lambda, u) \in U : F(\lambda, u) = 0, u \neq 0\}.$$

We say  $(\lambda_0, 0)$  is a **bifurcation point** for the equation (1) if  $(\lambda_0, 0) \in \overline{S}$  ( $\overline{S}$  is the closure of  $S$ ).

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**Theorem 8.1. (Krasnoselski-Rabinowitz Global Bifurcation Theorem)** [Rabinowitz, 1971, JFA] Let  $X$  be a Banach space, and let  $U$  be an open subset of  $\mathbb{R} \times X$  containing  $(\lambda_0, 0)$ . Suppose that  $L$  is a linear compact operator on  $X$ , and  $H(\lambda, u) : \overline{U} \rightarrow X$  is a compact operator such that  $\|H(\lambda, u)\| = o(\|u\|)$  as  $u \rightarrow 0$  uniformly for  $\lambda$  in any bounded interval. If  $1/\lambda_0$  is an eigenvalue of  $L$  with odd algebraic multiplicity, then  $(\lambda_0, 0)$  is a bifurcation point. Moreover if  $C$  is the connected component of  $\overline{S}$  which contains  $(\lambda_0, 0)$ , then one of the following holds:

- (i)  $C$  is unbounded in  $U$ ;
- (ii)  $C \cap \partial U \neq \emptyset$ ; or
- (iii)  $C$  contains  $(\lambda_i, 0) \neq (\lambda_0, 0)$ , such that  $\lambda_i^{-1}$  is also an eigenvalue of  $L$ .

# Leray-Schauder degree

Let  $X$  be a Banach space, and let  $U$  be an open bounded subset of  $X$ . Denote by  $K(\overline{U})$  the set of compact operators from  $\overline{U}$  to  $X$ , and define

$$M = \{(I - G, U, y) : U \subset X \text{ open bounded}, G \in K(\overline{U}), \text{ and } y \notin (I - G)(\partial U)\}.$$

Then the Leray-Schauder degree  $d : M \rightarrow \mathbf{Z}$  is a well-defined function, which satisfies the following properties:

- ①  $d(I, U, y) = 1$  if  $y \in U$ , and  $d(I, U, y) = 0$  if  $y \notin \overline{U}$ ;
- ② (Additivity)  $d(I - G, U, y) = d(I - G, U_1, y) + d(I - G, U_2, y)$  if  $U_1$  and  $U_2$  are disjoint open subsets of  $U$  so that  $y \notin (I - G)(\overline{U} \setminus (U_1 \cup U_2))$ ;
- ③ (Homotopy invariance) Suppose that  $h : [0, 1] \times \overline{U} \rightarrow X$  is compact and  $\gamma : [0, 1] \rightarrow X$  is continuous, and  $\gamma(t) \notin (I - G)(\partial U)$ , then  $D(t) = d(I - h(t, \cdot), U, \gamma(t))$  is a constant independent of  $t \in [0, 1]$ .
- ④ (Existence) If  $d(I - G, U, y) \neq 0$ , then there exists  $u \in U$  such that  $u - G(u) = y$ ;
- ⑤ If for  $G_1, G_2 \in K(\overline{U})$ ,  $G_1(u) = G_2(u)$  for any  $u \in \partial U$ , then  $d(I - G_1, U, y) = d(I - G_2, U, y)$ .

# Degree in finite dimensional spaces

For continuous  $f : U \equiv [-1, 1] \rightarrow \mathbb{R}$ ,  $d(I - f, U, 0)$  can be defined by  $d(I - f, U, 0) = \text{sgn}(f(-1)) \cdot \text{sgn}(f(1))$ , where  $\text{sgn}(y) = y/|y|$ . Another definition is  $d(I - f, U, 0) = \sum_{x \in U, x=f(x)} f'(x)$  for function  $f$  satisfying  $f'(x) \neq 0$  whenever  $f(x) = x$ . Here we must have  $x \neq f(x)$  for  $x = \pm 1$ .

For continuous  $f : U(\subset \mathbb{R}^n) \rightarrow \mathbb{R}^n$  ( $n \geq 2$ ),  $d(I - f, U, 0) = \sum_{x \in U, x=f(x)} \text{sgn}(\text{Det}(f'(x)))$  for function  $f$  satisfying  $\text{Det}(f'(x)) \neq 0$  whenever  $f(x) = x$ . Here we must have  $x \neq f(x)$  for  $x \in \partial U$ .

**Toy proof:** Let  $f(x, y) = (x^2, y^2)$ . Prove that  $f(x, y) = (3, 4)$  has a positive solution  $(x_1, y_1)$ .

1. Let  $U = \{(x, y) \in \mathbb{R}^2 : x > 0, y > 0, x^2 + y^2 = 6^2\}$ .
2. Prove that  $G_t(x, y) = I(x, y) - tf(x, y) = (x - tx^2, y - ty^2)$  has no solution  $(x_t, y_t) \in \partial U$  satisfying  $G_t(x_t, y_t) = (3, 4)$ .
3.  $G_0(x, y) = I(x, y) = (x, y)$  has a solution  $(x_0, y_0) = (3, 4) \in U$  such that  $G_0(x, y) = (3, 4)$  since  $(3, 4) \in U$ .
4.  $d(G_0, U, (3, 4)) = 1$  since  $\text{Det}(I) = 1$  and  $(3, 4)$  is the unique solution of  $G_0(x, y) = (3, 4)$ .
5.  $d(G_0, U, (3, 4)) = d(G_1, U, (3, 4))$  from the homotopy invariance property of Leray-Schauder degree, then  $d(G_1, U, (3, 4)) = 1$ .
6. Then  $G_1(x, y) = (3, 4)$  has a solution in  $U$ .

# Properties of Leray-Schauder degree

- 1 If  $L$  is a linear compact operator on  $X$ , then  $d(I - \lambda L, B_R(0), 0) = (-1)^\beta$ , where  $B_R(v)$  is a ball centered at  $v$  with radius  $R$ , and  $\beta$  is the sum of algebraic multiplicity of eigenvalues  $\mu$  of  $L$  satisfying  $\lambda\mu > 1$ .
- 2 Suppose that  $G \in K(\overline{U})$ ,  $u_0 \in U$  and  $R > 0$  such that  $u_0$  is the unique solution satisfies  $u - G(u) = 0$  in  $B_R(u_0)$ , then the derivative  $G'(u_0) : X \rightarrow X$  is a linear compact operator; if  $\lambda = 1$  is not an eigenvalue of  $G'(u_0)$ , then  $d(I - G, B_R(u_0), 0) = d(I - G'(u_0), B_R(0), 0)$  for some sufficiently small  $R > 0$  (this number is also called *fixed point index* of  $u_0$  with respect to  $G$ ).

**Example:**  $\Delta u + \lambda f(u) = 0$ ,  $x \in \Omega$ ,  $u = 0$ ,  $x \in \partial\Omega$ .

Suppose that  $f(0) = 0$ . What is the fixed point index of  $u = 0$ ?

1.  $K : (-\Delta)^{-1} : C^\alpha(\overline{\Omega}) \rightarrow C^\alpha(\overline{\Omega})$  is well defined as  $K(f) = u$  that  $u \in C_0^{2,\alpha}(\overline{\Omega})$  such that  $-\Delta u = f$  for any  $f \in C^\alpha(\overline{\Omega})$ .
2. For  $H(\lambda, u) = u - \lambda K(f(u)) = 0$ ,  $H_u(\lambda, u)[w] = w - \lambda K(f'(u))[w]$  and  $H_u(\lambda, 0)[w] = w - \lambda K(f'(0))[w]$ .
3. For  $L[w] = K(f'(0))[w] = \mu w$ , we have  $\mu\lambda\Delta w + \lambda f'(0)w = 0$  or  $\Delta w + (\mu\lambda)^{-1}\lambda f'(0)w = 0$ .
4. So for  $\mu\lambda > 1$ , let  $\rho_k < \lambda f'(0) < \rho_{k+1}$  then the fixed point index of 0 is  $\sum_{j=1}^k M(\rho_k)$ , where  $\rho_k$  is the  $k$ -th eigenvalue of  $\Delta\phi + \rho\phi = 0$ , and  $M(\rho_k)$  is the algebraic multiplicity of  $\rho_k$ .

# Krasnoselski Bifurcation Theorem

[Krasnoselski, 1964] Let  $X$  be a Banach space, and let  $U$  be an open subset of  $\mathbb{R} \times X$  containing  $(\lambda_0, 0)$ . Suppose that  $L$  is a linear compact operator on  $X$ , and  $H(\lambda, u) : \overline{U} \rightarrow X$  is a compact operator such that  $\|H(\lambda, u)\| = o(\|u\|)$  as  $u \rightarrow 0$  uniformly for  $\lambda$  in any bounded interval. If  $1/\lambda_0$  is an eigenvalue of  $L$  with odd algebraic multiplicity, then  $(\lambda_0, 0)$  is a bifurcation point.

**Proof.** Suppose not, then there exists a  $R > 0$  such that in the region  $O = \{(\lambda, u) : |\lambda - \lambda_0| \leq R, |u| \leq R\}$ , the only solutions of  $F(\lambda, u) = 0$  are  $\{(\lambda, 0) : |\lambda - \lambda_0| \leq R\}$ . We choose  $\lambda_-, \lambda_+$  so that  $\lambda_0 - R < \lambda_- < \lambda_0 < \lambda_+ < \lambda_0 + R$ . From the homotopy invariance of the Leray-Schauder degree,

$$d(F(\lambda_-, \cdot), B_\rho(0), 0) = d(F(\lambda_+, \cdot), B_\rho(0), 0),$$

for any  $\rho \in (0, R)$ . For  $\rho$  small enough,  $d(F(\lambda_\pm, \cdot), B_\rho(0), 0) = d(I - \lambda_\pm L, B_\rho(0), 0)$ . But on the other hand,

$$|d(I - \lambda_+ L, B_\rho(0), 0) - d(I - \lambda_- L, B_\rho(0), 0)| = 1,$$

since  $\lambda_0^{-1}$  is the only eigenvalue of  $L$  in between  $\lambda_-^{-1}$  and  $\lambda_+^{-1}$ , and the algebraic multiplicity of  $\lambda_0^{-1}$  is odd. That is a contradiction. Thus  $(\lambda_0, 0)$  is a bifurcation point.



# Rabinowitz Global Bifurcation Theorem

If  $C$  is the connected component of  $\overline{S}$  which contains  $(\lambda_0, 0)$ , then one of the following holds:

- (i)  $C$  is unbounded in  $U$ ;
- (ii)  $C \cap \partial U \neq \emptyset$ ; or
- (iii)  $C$  contains  $(\lambda_i, 0) \neq (\lambda_0, 0)$ , such that  $\lambda_i^{-1}$  is also an eigenvalue of  $L$ .

**Separation Lemma.** Let  $(M, d)$  be a compact metric space, and let  $A$  and  $B$  be close subsets of  $M$  such that  $A \cap B = \emptyset$ . Then there exist compact subsets  $M_A$  and  $M_B$  of  $M$  such that  $M_A \cup M_B = M$ ,  $M_A \cap M_B = \emptyset$ ,  $M_A \supset A$ , and  $M_B \supset B$ .

# Proof (1)

**Proof.** we assume the stated alternatives do not hold, then  $C$  is bounded in  $U$ ,  $C \cap \partial U = \emptyset$ , and  $C \cap \{(\lambda, 0) \in U\} = \{(\lambda_0, 0)\}$ . From the compactness of  $L$  and  $H$ ,  $C$  is compact since it is bounded. Let  $C_\varepsilon = \{(\lambda, u) \in U : \text{dist}((\lambda, u), C) < \varepsilon\}$ . Let  $A = C$  and  $B = S \cap \partial C_\varepsilon$ . From Separation Lemma, there exists compact  $M_A$  and  $M_B$  such that  $M_A \cap M_B = \emptyset$ ,  $M_A \cup M_B = S \cap \overline{C_\varepsilon}$ ,  $M_A \supset C$  and  $M_B \supset S \cap \partial C_\varepsilon$ . Hence there exists an open bounded  $U_0 = M_A$  such that

$$C \subset U_0 \subset \overline{U_0} \subset U, \quad \text{and} \quad \overline{S} \cap \partial U_0 = \emptyset. \quad (2)$$

Define  $U_0(\lambda) = \{u \in X : (\lambda, u) \in U_0\}$  for  $\lambda \in I$  where  $I = \{\lambda \in \mathbb{R} : (\{\lambda\} \times X) \cap U_0 \neq \emptyset\}$ . Then  $D(\lambda) = d(F(\lambda, \cdot), U_0(\lambda), 0)$  is constant for  $\lambda \in I$  since  $\overline{S} \cap \partial U_0 = \emptyset$  and the homotopy invariance of  $d(F, \Omega, 0)$ , where  $d(F(\lambda, \cdot), \Omega, 0)$  is the Leray-Schauder degree.

Since  $(\lambda_0, 0)$  is the only intersection of  $C$  with the line  $\{(\lambda, 0)\}$ ,  $U_0$  can be chosen so that  $U_0 \cap \{(\lambda, 0) \in U\} = [\lambda_0 - \delta, \lambda_0 + \delta] \times \{0\}$ , and no any point  $\lambda$  in  $[\lambda_0 - 2\delta, \lambda_0 + 2\delta]$  satisfies that  $\lambda^{-1}$  is an eigenvalue of  $L$ . We choose  $\lambda_\pm$  which satisfy  $\lambda_0 - \delta < \lambda_- < \lambda_0 < \lambda_+ < \lambda_0 + \delta$ . We choose  $\rho > 0$  small enough so that  $F(\lambda, u) \neq 0$  for  $\lambda \in [\lambda_+, \lambda_0 + 2\delta]$  and  $u \in B_\rho(0) \setminus \{0\}$ , and we also choose  $\lambda^* > \lambda_0 + 2\delta$  such that  $U_0(\lambda^*) = \emptyset$ .

## Proof (2)

From the homotopy invariance of the Leray-Schauder degree on  $U_0 \setminus ([\lambda_+, \lambda^*] \times \overline{B}_\rho(0))$ , we have

$$d(F(\lambda_+, \cdot), U_0(\lambda_+) \setminus \overline{B}_\rho(0), 0) = d(F(\lambda^*, \cdot), U_0(\lambda^*), 0) = 0. \quad (3)$$

For the same argument,

$$d(F(\lambda_-, \cdot), U_0(\lambda_-) \setminus \overline{B}_\rho(0), 0) = 0. \quad (4)$$

On the other hand, from the additivity of the Leray-Schauder degree,

$$D(\lambda_\pm) = d(F(\lambda_\pm, \cdot), U_0(\lambda_\pm) \setminus \overline{B}_\rho(0), 0) + d(F(\lambda_\pm, \cdot), B_\rho(0), 0). \quad (5)$$

Hence we obtain

$$d(F(\lambda_+, \cdot), B_\rho(0), 0) = d(F(\lambda_-, \cdot), B_\rho(0), 0). \quad (6)$$

For  $\rho > 0$  small enough,

$$d(F(\lambda_\pm, \cdot), B_\rho(0), 0) = d(I - \lambda_\pm L, B_\rho(0), 0). \quad (7)$$

From the formula of Leray-Schauder degree of  $I - \lambda L$ , we have

$$|d(I - \lambda_+ L, B_\rho(0), 0) - d(I - \lambda_- L, B_\rho(0), 0)| = 1, \quad (8)$$

But (8) is a contradiction with (7). Hence the alternatives in the theorem hold.

# Unilateral bifurcation theorem

[Rabinowitz, 1971, JFA], [Dancer, 1974, Indiana Math J], [Lopez-Gomez, 2000, book]

**Theorem 8.2.** Let  $X$  be a Banach space, and let  $U$  be an open subset of  $\mathbb{R} \times X$  containing  $(\lambda_0, 0)$ . Suppose that  $L$  is a linear compact operator on  $X$ , and  $H(\lambda, u) : \bar{U} \rightarrow X$  is a compact operator such that  $\|H(\lambda, u)\| = o(\|u\|)$  as  $u \rightarrow 0$  uniformly for  $\lambda$  in any bounded interval. Suppose that  $1/\lambda_0$  is an eigenvalue of  $L$  with algebraic multiplicity 1. We define  $\Gamma_+ = \{(\lambda(s), u(s)) : s \in (0, \epsilon)\}$  and  $\Gamma_- = \{(\lambda(s), u(s)) : s \in (-\epsilon, 0)\}$ . Let  $\mathcal{C}$  be a connected component of  $\bar{S}$  where  $S = \{(\lambda, u) \in V : H(\lambda, u) = 0, u \neq 0\}$  containing  $(\lambda_0, 0)$ . Let  $\mathcal{C}^+$  (resp.  $\mathcal{C}^-$ ) be the connected component of  $\mathcal{C} \setminus \Gamma_-$  which contains  $\Gamma_+$  (resp. the connected component of  $\mathcal{C} \setminus \Gamma_+$  which contains  $\Gamma_-$ ). Then each of the sets  $\mathcal{C}^+$  and  $\mathcal{C}^-$  satisfies one of the following:

- (i) it is unbounded;
- (ii) it contains a point  $(\lambda_*, 0)$  with  $\lambda_* \neq \lambda_0$ ; or
- (iii) it contains a point  $(\lambda, z)$ , where  $z \neq 0$  and  $z \in Z$  which any complement of  $\text{span}\{w_0\} = \mathcal{N}(H_u(\lambda_0, 0))$  in  $X$ .



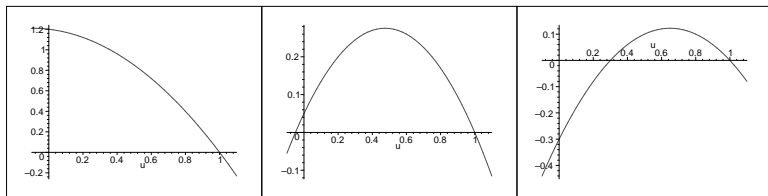
# Application 1: Reaction-diffusion population model

$$\begin{cases} \frac{\partial u}{\partial t} = \mathcal{D}\Delta u + uf(x, u), & x \in \Omega, \quad t > 0, \\ u(x, t) = 0, & x \in \partial\Omega, \quad t > 0, \\ u(x, 0) = u_0(x) \geq 0, & x \in \Omega. \end{cases}$$

$u(x, t)$ : population density at position  $x$  and time  $t$

$\Omega$ : a bounded habitat,  $u = 0$  on boundary  $\partial\Omega$ : hostile exterior environment

$f(x, u)$ : heterogeneous growth rate per capita



$f(x, u)$ : (a) logistic; (b) weak Allee effect; (c) strong Allee effect.

# Bifurcation problem

$$\Delta u + \lambda u f(x, u) = 0, \quad x \in \Omega, \quad u = 0, \quad x \in \partial\Omega.$$

$u = 0$  is always a solution for any  $\lambda > 0$ ,  $\lambda_1(f, \Omega)$  (minimal patch size) is the principal eigenvalue of  $\Delta\psi + \lambda f(x, 0)\psi = 0$ ,  $x \in \Omega$ ,  $\psi = 0$ ,  $x \in \partial\Omega$ . We consider positive solutions only.

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Logistic case: a supercritical transcritical bifurcation occurs at  $\lambda_1(f, \Omega)$ ; for  $\lambda > \lambda_1$ , there is a unique steady state which is globally stable. [\[Cantrell-Cosner, 2003\]](#)



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Weak Allee effect case:

- (A) a subcritical (backward) transcritical bifurcation occurs at  $\lambda_1(f, \Omega) > 0$ ;
- (B) for  $\lambda \in (\lambda_*, \lambda_1)$ , there are at least two steady state solutions (bistability);
- (C) a saddle-node bifurcation occurs at  $\lambda_*$  (at least when  $\Omega$  is a ball);
- (D) for  $\lambda$  large, it is similar to logistic case. [Shi-Shivaji, JMB, 2006]

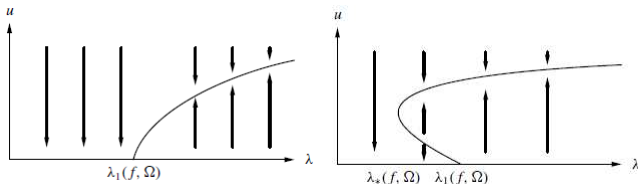
The solution curve near  $(\lambda, u) = (\lambda_1, 0)$  is  $\{(\lambda(s), u(s)) : 0 < s < \delta\}$ , where  $\delta > 0$  is a constant,  $\lambda(s) = \lambda_1(f, \Omega) + \eta(s)$ ,  $u(s) = s\varphi_1 + sv(s)$ ,  $0 < s < \delta$ ,  $\eta(0) = 0$  and  $v(0) = 0$ , and

$$\eta'(0) = -2[\lambda_1(f, \Omega)]^2 \frac{\int_{\Omega} f_u(x, 0)\varphi_1^3(x)dx}{\int_{\Omega} |\nabla\varphi_1(x)|^2 dx}.$$

Allee effect caused by diffusion (ODE with weak Allee effect is similar to logistic case); danger of hysteresis. [Jiang-Shi, book chapter, 2009]

# Bifurcation Diagrams

$$\Delta u + \lambda u f(x, u) = 0, \quad x \in \Omega, \quad u = 0, \quad x \in \partial\Omega,$$

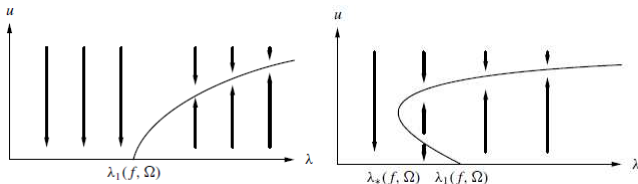


(Left) logistic; (Right) weak Allee effect;

**Proposition:** the bifurcating branch belongs to a global continuum in  $C^\alpha(\overline{\Omega})$ .

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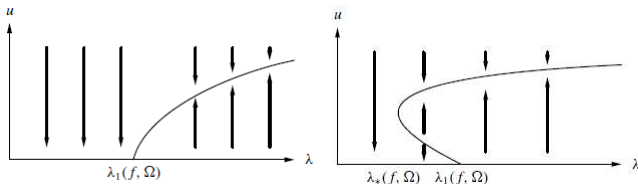
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**Proposition:** the bifurcating branch belongs to a global continuum in  $C^\alpha(\overline{\Omega})$ .

1.  $K = (-\Delta)^{-1} : C^\alpha(\overline{\Omega}) \rightarrow C^\alpha(\overline{\Omega})$  is well defined as  $K(f) = u$  that  $u \in C_0^{2,\alpha}(\overline{\Omega})$  such that  $-\Delta u = f$  for any  $f \in C^\alpha(\overline{\Omega})$ .

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2. We apply  $K$  to the equation, and we consider

$$G(\lambda, u) \equiv u - \lambda K u f(x, u) = 0,$$

where  $u \in C^\alpha(\overline{\Omega})$ .

# Global Branch

- 1 Let  $E = C^\alpha(\overline{\Omega})$ , and let  $S = \{(\lambda, u) \in \mathbb{R}^+ \times E : G(\lambda, u) = 0, u \neq 0\}$ . Then there exists a connected component  $\mathcal{C}$  of  $\overline{S}$  such that  $(\lambda_1, 0) \in \mathcal{C}$ .

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- 2 Let  $E^+ = \{u \in E : u(x) \geq 0 \text{ in } \Omega\}$ . Then  $\mathcal{C}_+ = \mathcal{C} \cap (\mathbb{R}^+ \times E^+)$  is unbounded.

# Global Branch

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- 2 Let  $E^+ = \{u \in E : u(x) \geq 0 \text{ in } \Omega\}$ . Then  $\mathcal{C}_+ = \mathcal{C} \cap (\mathbb{R}^+ \times E^+)$  is unbounded.
- 3 If  $f(x, u)$  satisfies  $f(x, u) < 0$  for  $u > 1$ , then  $0 < u(x) < 1$  for  $x \in \Omega$ , where  $u$  is any positive solution of

$$\Delta u + \lambda u f(x, u) = 0, \quad x \in \Omega, \quad u = 0, \quad x \in \partial\Omega.$$

Therefore the projection of  $\mathcal{C}_+$  to  $\lambda$ -axis is unbounded in  $\mathbb{R}^+$ , and hence it contains  $(\lambda_1, \infty)$ . This proves the existence of a positive solution for any  $\lambda > \lambda_1$ .

# Uniqueness in logistic case

Assume  $f_u(x, u) \leq 0$  (logistic case). A positive solution to

$$\Delta u + \lambda u f(x, u) = 0, \quad x \in \Omega, \quad u = 0, \quad x \in \partial\Omega,$$

is stable if all eigenvalues  $\mu_i$  of

$$-\Delta \phi - \lambda f(x, u) \phi - \lambda u f_u(x, u) \phi = \mu \phi, \quad x \in \Omega, \quad \phi = 0, \quad x \in \partial\Omega,$$

are positive.

From  $u$ 's equation,  $u$  is the principal eigenfunction of the eigenvalue problem (with  $\eta = 0$ ):

$$-\Delta \psi - \lambda f(x, u) \psi = \eta \psi, \quad x \in \Omega, \quad \psi = 0, \quad x \in \partial\Omega,$$

But

$$\begin{aligned} \mu_1 &= \min_{\phi \in W_0^{1,2}(\Omega), \phi \neq 0} \frac{\int_{\Omega} (|\nabla \phi|^2 - \lambda f(x, u) \phi^2 - \lambda u f_u(x, u) \phi^2) dx}{\int_{\Omega} \phi^2 dx} \\ &> \min_{\psi \in W_0^{1,2}(\Omega), \psi \neq 0} \frac{\int_{\Omega} (|\nabla \psi|^2 - \lambda f(x, u) \psi^2) dx}{\int_{\Omega} \psi^2 dx} = \eta_1 = 0, \end{aligned}$$

So **any** positive solution  $u$  is stable, hence non-degenerate.



## Application 2: 1-D scalar problem

[Rabinowitz, 1972, book chapter]

Consider

$$\begin{aligned} -(p(x)u')' + q(x)u &= \lambda a(x)u + \lambda F(x, u, u'), \quad 0 < x < \pi, \\ a_0 u(0) + b_0 u'(0) &= 0, \quad a_1 u(1) + b_1 u'(1) = 0, \end{aligned}$$

where  $a_0, b_0, a_1, b_1$  satisfy  $(a_0^2 + b_0^2)(a_1^2 + b_1^2) \neq 0$ . Let  $E$  be the set of functions in  $C^1[0, \pi]$  satisfying boundary condition. Let  $S_k^+$  be the set of  $\phi \in E$  such that  $\phi$  has exactly  $k - 1$  simple zeros in  $(0, \pi)$ , all zeros of  $\phi$  in  $[0, \pi]$  are simple, and  $\phi$  is positive near  $x = 0$ . Set  $S_k^- = -S_k^+$  and  $S_k = S_k^+ \cup S_k^-$ . Let  $S$  be the closure in  $\mathbb{R} \times E$  of the set of nontrivial solutions of the equation. It is known that the eigenvalue problem

$$\begin{aligned} -(p(x)\phi')' + q(x)\phi &= \lambda a(x)\phi, \quad 0 < x < \pi, \\ a_0 \phi(0) + b_0 \phi'(0) &= 0, \quad a_1 \phi(1) + b_1 \phi'(1) = 0, \end{aligned}$$

has a sequence of eigenvalues  $\lambda_1 < \lambda_2 \leq \lambda_3 \leq \dots \rightarrow \infty$ .

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has a sequence of eigenvalues  $\lambda_1 < \lambda_2 \leq \lambda_3 \leq \dots \rightarrow \infty$ .

**Theorem.** If  $F(x, u, u') = o(|u| + |u'|)$  near  $(u, u') = (0, 0)$ , then for each positive integer  $k > 0$ ,  $S$  contains a connected component  $C_k$ , which meets  $(\lambda_k, 0)$  and is unbounded in  $\mathbb{R} \times S_k$ .

In particular, if the equation has only trivial solutions when  $\lambda > 0$ , and all solutions are uniformly bounded, then for  $\lambda > \lambda_k$ , the problem has at least  $k$  distinct solutions, with one each in  $S_k$ .

# Application 3: Global Turing Bifurcation

**Theorem:** Suppose that  $f(u_0, v_0) = g(u_0, v_0) = 0$ , and at  $(u_0, v_0)$ ,

(A)  $f_u < 0$  (inhibitor),  $g_v > 0$  (activator);

(B)  $D_1 = f_u g_v - f_v g_u > 0$  and  $f_u + g_v < 0$ .

For fixed  $\lambda > 0$ , if  $d_k(\lambda) \equiv \frac{\lambda[g_v k^2 - \lambda D_1]}{k^2(k^2 - \lambda f_u)} \neq d_j(\lambda)$  for any  $j \neq k$ ,

(i)  $d = d_k$  is a bifurcation point where a continuum  $\Sigma$  of non-trivial solutions of

$$\begin{cases} u_{xx} + \lambda f(u, v) = 0, & dv_{xx} + \lambda g(u, v) = 0, & x \in (0, \ell\pi), \\ u_x(0) = u_x(\ell\pi) = v_x(0) = v_x(\ell\pi) = 0, \end{cases}$$

bifurcates from the line of trivial solutions  $(d, u_0, v_0)$ ;

(ii) The continuum  $\Sigma$  is either unbounded in the space of  $(d, u, v)$ , or it connects to another  $(d_j(\lambda), u_0, v_0)$ ;

(iii)  $\Sigma$  is locally a curve near  $(d_k(\lambda), u_0, v_0)$  in form of

$(d, u, v) = (d(s), u_0 + sA \cos(kx) + o(s), v_0 + sB \cos(kx) + o(s))$ ,  $|s| < \delta$ , and

$d'(0) = 0$  thus the bifurcation is of pitchfork type ( $d''(0)$  can be computed in term of  $D^3(f, g)$ ).

[Rabinowitz, 1971, JFA],

[Shi-Wang, 2009, JDE] [Shi, 2009, Frontier Math. China]

# Turing bifurcation in CIMA model

$$\begin{cases} u_t = u_{xx} + 5\alpha - u - \frac{4uv}{1+u^2}, & x \in (0, \ell\pi), \quad t > 0, \\ v_t = m \left( dv_{xx} + u - \frac{uv}{1+u^2} \right), & x \in (0, \ell\pi), \quad t > 0, \\ u_x(x, t) = v_x(x, t) = 0, & x = 0, \ell\pi, \quad t > 0, \\ u(x, 0) = u_0(x), \quad v(x, 0) = v_0(x), & x \in (0, \ell\pi), \end{cases} \quad (9)$$

Constant equilibrium:  $(u_*, v_*) = (\alpha, 1 + \alpha^2)$

Jacobian at  $(u_*, v_*)$ :  $J = \frac{1}{1 + \alpha^2} \begin{pmatrix} 3\alpha^2 - 5 & -4\alpha \\ 2\alpha^2 & -\alpha \end{pmatrix}$ .

Assume  $0 < 3\alpha^2 - 5 < \alpha$  (or  $1.291 < \alpha < 1.468$ )

$f_u > 0$ ,  $g_v < 0$ ,  $D_1 = f_u g_v - f_v g_u > 0$  and  $f_u + g_v < 0$ .

Bifurcation points:  $d_j = \frac{\alpha}{1 + \alpha^2} \cdot \frac{5 + \lambda_j}{\lambda_j(f_0 - \lambda_j)}$ ,

where  $f_0 = \frac{3\alpha^2 - 5}{1 + \alpha^2}$ , and  $\lambda_j = j^2/\ell^2$ .

[Ni-Tang, 2005] also true for higher dimensions

# Global Turing Bifurcation for CIMA reaction

[Ni-Tang, 2005] *Trans. Amer. Math. Soc.*:

- (A) For  $d > 0$  small,  $(u_*, v_*)$  is the only steady state solution;
- (B) All non-negative steady state solution satisfies  $0 < u(x) < 5\alpha$ ,  $0 < v(x) < 1 + 25\alpha^2$ .

[Jang-Ni-Tang, 2004] *J. Dynam. Diff. Equa.*:

- (C) Each connected component bifurcated from  $(d_j, u_*, v_*)$  is unbounded in the space of  $(d, u, v)$ , and its projection over  $d$ -axis covers  $(d_j, \infty)$ .
- (D) For each  $d > \min\{d_j\}$  and  $d \neq d_k$ , there exists a non-constant steady state solution.

[Jin-Shi-Wei-Yi, to appear] Bifurcation with  $\alpha$  as parameter.

# Bifurcation in CIMA system

$$\begin{cases} u_{xx} + 5\alpha - u - \frac{4uv}{1+u^2} = 0, & x \in (0, \ell\pi), \\ dv_{xx} + u - \frac{uv}{1+u^2} = 0, & x \in (0, \ell\pi), \\ u_x(0) = v_x(0) = u_x(\ell\pi) = v_x(\ell\pi) = 0. \end{cases}$$

$$D(\alpha, p) := d(1 + \alpha^2)p^2 - p[d(3\alpha^2 - 5) - \alpha] + 5\alpha = 0$$

$$\text{Bifurcation points: } (p = j^2/\ell^2), \alpha(p) = \frac{p + 5 + \sqrt{(p+5)^2 + 4d^2p^2(3-p)(p+5)}}{2dp(3-p)}.$$

For  $0 < j^2/\ell^2 < 3$ , there are finitely many  $j$  points  $\alpha_j^S = \alpha_j^S(d, \ell)$ ,  $1 \leq j \leq n$ , satisfying

$$\alpha_* < \alpha_1^S < \alpha_2^S < \cdots < \alpha_n^S < \infty,$$

with  $\alpha_j^S = \alpha_2(j^2/\ell^2)$ , and  $\alpha = \alpha_n^S$  is a possible bifurcation point.

- 1 There exists a  $C^\infty$  smooth curve  $\Gamma_j$  of solutions bifurcating from  $(\alpha, u, v) = (\alpha_j^S, u_{\alpha_j^S}, v_{\alpha_j^S})$ , with  $\Gamma_j$  contained in a global branch  $\mathcal{C}_j$  of solutions;
- 2 Near  $(\alpha, u, v) = (\alpha_j^S, u_{\alpha_j^S}, v_{\alpha_j^S})$ ,  $\Gamma_j = \{(\alpha_j(s), u_j(s), v_j(s)) : s \in (-\epsilon, \epsilon)\}$ , where  $u_j(s) = \alpha_j^S + sa_j \cos(jx/\ell) + s\psi_{1,j}(s)$ ,  $v_j(s) = (1 + \alpha_j^S)^2 + sb_j \cos(jx/\ell) + s\psi_{2,j}(s)$  for  $s \in (-\epsilon, \epsilon)$  for some  $C^\infty$  smooth functions  $\alpha_j, \psi_{1,j}, \psi_{2,j}$  such that  $\alpha_j(0) = \alpha_j^S$  and  $\psi_{1,j}(0) = \psi_{2,j}(0) = 0$ ;
- 3 Each  $\mathcal{C}_j$  is unbounded: the projection of  $\mathcal{C}_j$  on the  $\alpha$ -axis contains  $(\alpha_j^S, \infty)$ .

# Unbounded branches

Since  $0 < u(x) < 5\alpha$  and  $0 < v(x) < 1 + 25\alpha^2$ , then  $\mathcal{C}_j$  must remain bounded for finite  $\alpha$ . Suppose that the projection of  $\mathcal{C}_j$  in  $\alpha$ -axis is bounded. Then  $\mathcal{C}_j$  must contain another bifurcation point  $(\alpha_i^S, \alpha_i^S, 1 + (\alpha_i^S)^2)$  for some  $i \neq j$ . Indeed  $\mathcal{C}_j$  contains finitely many bifurcation points in form of  $(\alpha_i^S, \alpha_i^S, 1 + (\alpha_i^S)^2)$ , since there are only finitely  $i \in \mathbb{N}$  such that  $i^2/\ell^2 < 3$  for fixed  $\ell > 0$ . Among these finitely many  $\alpha_i^S$ , there is one with largest index  $i_M$ . Notice that the equation is also well-defined for the interval  $(0, \ell\pi/i_M)$ , and the bifurcation points (depending on the length) have the relation

$$\alpha_{i_M}^S(\ell\pi) = \alpha_2(i_M^2/\ell^2) = \alpha_1^S(\ell\pi/i_M) := \alpha^M.$$

Hence  $\alpha^M$  is also a bifurcation point for the equation with interval  $(0, \ell\pi/i_M)$ . From global bifurcation theorem, the global branch  $\mathcal{C}_1^M$  bifurcating from  $\alpha = \alpha^M$  for the equation with interval  $(0, \ell\pi/i_M)$  is also unbounded or contains another bifurcation point. But any solution with interval  $(0, \ell\pi/i_M)$  can be extended to  $(0, \ell\pi)$  by reflection, hence that  $\mathcal{C}_1^M$  is unbounded implies that  $\mathcal{C}_j$  is unbounded, which contradicts our assumption. Or  $\mathcal{C}_1^M$  contains another bifurcation point  $\alpha_k^S(\ell\pi/i_M)$ , but that will imply  $\alpha_{ki_M}^S(\ell\pi) = \alpha_k^S(\ell\pi/i_M)$  is on the branch  $\mathcal{C}_j$ , and clearly  $ki_M > i_M$  since  $k > 1$ , which contradicts with the maximality of  $i_M$ . Therefore the projection of  $\mathcal{C}_j$  in  $\alpha$ -axis is not bounded.

# The weakness of Rabinowitz Theorem

It requires strong compactness. For applications in PDEs, it usually requires to take inverse of  $\Delta$  operators or more general elliptic operators. For some applications with cross-diffusion or nonlinear boundary conditions, taking inverse operators are not easy.

Cross-diffusion equation: [\[Shigesada-Kawasaki-Teramoto, 1979\]](#)

$$\begin{cases} \Delta[(1 + \alpha v)u] + u(\lambda - u - bv) = 0, & x \in \Omega, \\ \Delta[(1 + \beta u)v] + v(\mu + cu - v) = 0, & x \in \Omega, \\ u = v = 0, & x \in \partial\Omega. \end{cases}$$

Problem with nonlinear boundary condition

$$\begin{cases} u'' - f(u)v = 0, & x \in (0, 1), \\ \lambda v'' - \chi(v\psi'(u)u')' + (kf(u) - \theta - \beta v)v = 0, & x \in (0, 1), \\ u'(0) = 0, \quad u'(1) = h(1 - u(1)), \\ \lambda v' - \chi v\psi'(u)u' = 0, & x = 0, 1. \end{cases}$$



# Global Bifurcation From Simple Eigenvalue

## Theorem [Crandall-Rabinowitz, 1971, JFA]

Let  $F : \mathbb{R} \times X \rightarrow Y$  be continuously differentiable. Suppose that  $F(\lambda, u_0) = 0$  for  $\lambda \in \mathbb{R}$ , the partial derivative  $F_{\lambda u}$  exists and is continuous. At  $(\lambda_0, u_0)$ ,  $F$  satisfies

**(F1)**  $\dim N(F_u(\lambda_0, u_0)) = \operatorname{codim} R(F_u(\lambda_0, u_0)) = 1$ , and

**(F3)**  $F_{\lambda u}(\lambda_0, u_0)[w_0] \notin R(F_u(\lambda_0, u_0))$ , where  $w_0 \in N(F_u(\lambda_0, u_0))$ ,

Then the solutions of  $F(\lambda, u) = 0$  near  $(\lambda_0, u_0)$  consists precisely of the curves  $u = u_0$  and  $(\lambda(s), u(s))$ ,  $s \in I = (-\delta, \delta)$ , where  $(\lambda(s), u(s))$  are  $C^1$  functions such that  $\lambda(0) = \lambda_0$ ,  $u(0) = u_0$ ,  $u'(0) = w_0$ .

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[Pejsachowicz-Rabier, 1998] [Shi-Wang, 2009, JDE]

If in addition,  $F_u(\lambda, u)$  is a Fredholm operator for all  $(\lambda, u) \in \mathbb{R} \times X$ , then the curve  $\{(\lambda(s), u(s)) : s \in I\}$  is contained in  $\mathcal{C}$ , which is a connected component of  $S = \{(\lambda, u) \in \mathbb{R} \times X : F(\lambda, u) = 0, u \neq u_0\}$ ; and either  $\mathcal{C}$  is not compact, or  $\mathcal{C}$  contains a point  $(\lambda_*, 0)$  with  $\lambda_* \neq \lambda_0$ .

# Unilateral Theorem

Suppose that all conditions above are satisfied. Let  $\mathcal{C}$  be defined as above. We define  $\Gamma_+ = \{(\lambda(s), u(s)) : s \in (0, \epsilon)\}$  and  $\Gamma_- = \{(\lambda(s), u(s)) : s \in (-\epsilon, 0)\}$ . In addition we assume that

- 1  $F_u(\lambda, u_0)$  is continuously differentiable in  $\lambda$  for  $(\lambda, u_0) \in V$ ;
- 2 The norm function  $u \mapsto \|u\|$  in  $X$  is continuously differentiable for any  $u \neq 0$ ;
- 3 For  $k \in (0, 1)$ , if  $(\lambda, u_0)$  and  $(\lambda, u)$  are both in  $V$ , then  $(1 - k)F_u(\lambda, u_0) + kF_u(\lambda, u)$  is a Fredholm operator.

Let  $\mathcal{C}^+$  (resp.  $\mathcal{C}^-$ ) be the connected component of  $\mathcal{C} \setminus \Gamma_-$  which contains  $\Gamma_+$  (resp. the connected component of  $\mathcal{C} \setminus \Gamma_+$  which contains  $\Gamma_-$ ). Then each of the sets  $\mathcal{C}^+$  and  $\mathcal{C}^-$  satisfies one of the following: (i) it is not compact; (ii) it contains a point  $(\lambda_*, u_0)$  with  $\lambda_* \neq \lambda_0$ ; or (iii) it contains a point  $(\lambda, u_0 + z)$ , where  $z \neq 0$  and  $z \in Z$ .

# Fredholm Operators of Index Zero

Quasilinear elliptic systems with nonlinear boundary conditions are Fredholm operators of index zero

**Theorem [Shi-Wang, 2009, JDE]**

Suppose that  $p > n$ ,  $\partial\Omega \in C^3$ , and the regularity assumption above holds. Let  $U$  be an open connected set of  $\mathbb{R} \times (W^{2,p}(\Omega))^N$ . Assume that for each fixed  $(\lambda, u) \in U$ ,  $D_u T(\lambda, u) = (D_u A(\lambda, u), D_u B(\lambda, u))$  is elliptic on  $\overline{\Omega}$ , and that for a particular  $(\lambda_0, u_0) \in U$ ,  $D_u T(\lambda_0, u_0)$  satisfies Agmon's condition at a  $\theta_0$ , then the Fredholm index of  $D_u T(\lambda, u)$  is 0 for all  $(\lambda, u) \in U$ .

It will have many applications in reaction-diffusion systems in mathematical biology, physics, and chemistry.

# Application

Cross-diffusion system:

$$\begin{cases} \Delta[(1 + \alpha_1 u + \alpha_2 v)u] + u(\lambda - u - bv) = 0, & x \in \Omega, \\ \Delta[(1 + \beta_1 u + \beta_2 v)v] + v(\mu + cu - v) = 0, & x \in \Omega, \\ u = v = 0, & x \in \partial\Omega. \end{cases}$$

Competing species with passive diffusion, self-diffusion, cross-diffusion.

[Shigesada, Kawasaki and Teramoto, 1979]

[Nakashima, Yamada, 1996] [Kuto, Yamada, 2004]:  $\alpha_1 = \beta_2 = 0$

**Their idea:**  $U = (1 + \alpha_2 v)u$ ,  $V = (1 + \beta_1 u)v$ , then the system becomes semilinear but with messy nonlinearities.

We prove the existence of a bounded branch of coexistence solutions which connecting the two semi-trivial solution branches via our new global bifurcation theorem. Our method is definitely more direct.